## Formulae Sheet for Economics Part IIA Paper 6

You should be able to recall these formulae in the exam, in whatever form you prefer. I cannot guarantee that the list is exhaustive, but it should cover the great majority of the formulae you will need.

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## Calculus

$$\frac{d}{dx}\ln(kx) = \frac{1}{x}$$

$$\frac{d}{dx}e^{kx} = ke^{kx}$$

Differentiation of a product:  $\frac{d(uv)}{dx} = v \frac{du}{dx} + u \frac{dv}{dx}$ 

Integration by parts:  $\int u \frac{dv}{dx} dx = [uv] - \int v \frac{du}{dx} dx$ 

Quadratic formula:  $ax^2 + bx + c = 0$  has solution  $x = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$ 

Definition of a convex function:  $f((1-t)a+tb) \le (1-t)f(a)+tf(b)$  for  $0 \le t \le 1$ 

Total differential:  $df = \frac{\partial f}{\partial x} dx + \frac{\partial f}{\partial y} dy$ 

 $\frac{\partial^2 f}{\partial x \partial y} = \frac{\partial^2 f}{\partial y \partial x}$  unless f is discontinuous

Implicit function theorem: along an isoquant of f:  $\frac{dy}{dx} = -\frac{\frac{\partial f}{\partial x}}{\frac{\partial f}{\partial y}}$ 

Homogeneous function  $f(x_1, x_2, ..., x_n)$ , of degree m obeys:

$$f(tx_1, tx_2, ..., tx_n) = t^m f(x_1, x_2, ..., x_n)$$
 and (Euler)  $x_1 \frac{\partial f}{\partial x_1} + x_2 \frac{\partial f}{\partial x_2} + ... + x_n \frac{\partial f}{\partial x_n} = mf$ 

Binomial series:  $(1+x)^n = 1 + nx + \frac{n(n-1)x^2}{2!} + \frac{n(n-1)(n-2)x^3}{3!} + \dots$ 

or: 
$$(a+b)^n = a^n + na^{n-1}b + \frac{n(n-1)a^{n-2}b^2}{2!} + \frac{n(n-1)(n-2)a^{n-3}b^3}{3!} + \dots + nab^{n-1} + b^n$$

Maclaurin series: 
$$f(x) = f(0) + xf'(0) + \frac{x^2 f''(0)}{2!} + \frac{x^3 f'''(0)}{3!} + \dots$$

Taylor series in 1D: 
$$f(a+x) = f(a) + xf'(a) + \frac{x^2 f''(a)}{2!} + \frac{x^3 f'''(a)}{3!} + \dots$$

exponential series: 
$$e^x = 1 + x + \frac{x^2}{2!} + \frac{x^3}{3!} + \dots$$

log series: 
$$ln(1+x) = x - \frac{x^2}{2} + \frac{x^3}{3} + ...$$

Taylor series in 2D:

$$f(a+x,b+y) = f(a,b) + \left(x\frac{\partial f}{\partial x}\Big|_{(a,b)} + y\frac{\partial f}{\partial y}\Big|_{(a,b)}\right) + \frac{1}{2!}\left(x^2\frac{\partial^2 f}{\partial x^2}\Big|_{(a,b)} + 2xy\frac{\partial^2 f}{\partial x\partial y}\Big|_{(x,y)} + y^2\frac{\partial^2 f}{\partial y^2}\Big|_{(a,b)}\right) + \dots$$

ie:

$$f(a+x,b+y) = f(a,b) + (x,y) \begin{pmatrix} \frac{\partial f}{\partial x} \\ \frac{\partial f}{\partial y} \end{pmatrix}_{(a,b)} + \frac{1}{2!} (x,y) \begin{pmatrix} \frac{\partial^2 f}{\partial x^2} & \frac{\partial^2 f}{\partial x \partial y} \\ \frac{\partial^2 f}{\partial x \partial y} & \frac{\partial^2 f}{\partial y^2} \end{pmatrix}_{(a,b)} \begin{pmatrix} x \\ y \end{pmatrix} + \dots$$

l'Hôpital: 
$$\lim_{x\to a} \frac{f(x)}{g(x)} = \lim_{x\to a} \frac{f'(x)}{g'(x)}$$
 when  $\lim_{x\to a} f(x) = \lim_{x\to a} g(x) = both \ 0$  or  $both \ \pm \infty$ 

$$\lim_{n\to\infty} (1+x/n)^n = e^x$$

Geometric progression: 
$$\sum_{i=0}^{\infty} ar = \frac{a}{1-r}$$

& you should either know, or be able to work out from this, that  $\sum_{i=0}^{n} ar = \frac{a(1-r^{n+1})}{1-r}$ 

In whatever form you choose to remember them: Mean Value Theorem, Envelope Theorem, Shephard's Lemma, Roy's Identity.

## **Statistics**

$$P(A \cup B) = P(A) + P(B) - P(A \cap B)$$

$$P(A \cap B) = P(A \mid B)P(B) = P(B \mid A)P(A)$$

Bayes: 
$$P(A \mid B) = \frac{P(B \mid A)P(A)}{P(B)}$$

 $P(A \cap B) = P(A)P(B)$  if A and B are independent

$$P(A \cap B) + P(A \cap \overline{B}) = P(A)$$

Binomial probability of r successes n trials =  ${}^{n}C_{r}p^{r}(1-p)^{n-r}$  where p = probability of success in any one trial.

Poisson probability of r successes =  $\frac{\lambda^r e^{-\lambda}}{r!}$ 

Normal distribution is 
$$N(\mu, \sigma^2) = \frac{1}{\sqrt{2\pi\sigma^2}} e^{\frac{-(x-\mu)^2}{2\sigma^2}}$$

Beta distribution  $Beta(\alpha, \beta) = Kx^{\alpha-1}(1-x)^{\beta-1}$  (K=normalising constant) for  $0 \le x \le 1$ 

Conditional density function:  $g(y \mid x) = \frac{f(x, y)}{h(x)}$  where f(x,y) = joint density function

Marginal density function:  $h(x) = \int f(x, y) dy$ 

Continuous form of Bayes' Theorem:  $f(x \mid data) = \frac{prob(data \mid x) f(x)}{\int prob(data \mid x) f(x) dx}$ 

Uncentred and centred  $r^{th}$  moments:  $\mu_r = E(x^r)$  and  $\mu_r = E((x-\mu)^r)$ 

$$E(x^r) = \sum_{x} x^r \Pr(x)$$
 (discrete) or  $E(x^r) = \int x^r f(x) dx$  (continuous)

$$E(X_1 + X_2) = E(X_1) + E(X_2)$$

$$E(X_1 + k) = E(X_1) + k$$

$$E(kX_1) = kE(X_1)$$

 $E(X_1X_2) = E(X_1)E(X_2)$  if  $X_1$  and  $X_2$  are independent

$$var(X) = E[(X - E(X))^{2}] = E(X^{2}) - [E(X)]^{2}$$

$$\operatorname{var}(X_1 + k) = \operatorname{var}(X_1)$$

$$var(kX_1) = k^2 var(X_1)$$

 $var(X_1 \pm X_2) = var(X_1) + var(X_2)$  if  $X_1$  and  $X_2$  are independent

 $\operatorname{var}(X_1 \pm X_2) = \operatorname{var}(X_1) + \operatorname{var}(X_2) \pm 2\operatorname{covar}(X_1, X_2)$  more generally

Moment generating function:  $M_X(t) = E(e^{tx})$  and  $\frac{d^r M_X(t)}{dt^r}\Big|_{t=0} = \mu_r$ 

$$M_{X_1+X_2+X_{31}+...}(t) = M_{X_1}(t)M_{X_2}(t)M_{X_3}(t)...$$

$$M_{X+a}(t) = e^{at} M_X(t)$$

$$M_{hX}(t) = M_X(bt)$$

Moment generating function of N(0,1) is  $e^{t^2/2}$ 

Cramer-Rao lower bound:  $\operatorname{var}(\widehat{\theta}) \ge \left[ -E\left(\frac{d^2 \log(L)}{d\theta^2}\right) \right]^{-1}$ 

Chebyshev: 
$$\Pr(|X - \mu| \ge \varepsilon) \le \frac{\sigma^2}{\varepsilon^2}$$

## Linear Algebra

$$A + (B + C) = (A + B) + C$$

$$A(B+C) = AB + AC$$

$$(A+B)^T = A^T + B^T$$

 $AB \neq BA$ , in general

$$A^{-1}A = AA^{-1} = I$$

$$A(BC) = (AB)C$$

$$(AB)^T = B^T A^T$$

$$(AB)^{-1} = B^{-1}A^{-1}$$

$$\det(A^T) = \det(A)$$

$$\det(AB) = \det(A)\det(B)$$

$$\det(A^{-1}) = \frac{1}{\det(A)}$$

Rules of determinants:

Can subtract a multiple of any row from any other row without affecting value Can expand along any row

Swapping two rows reverses the sign of the determinant Multiplying all terms in a single row by  $\lambda$  multiplies the determinant by  $\lambda$  Any rule that applies to rows also applies to columns

Formula for the inverse of a matrix, using cofactors:  $A^{-1} = \frac{adj(A)}{\det(A)}$  and hence  $A^{-1}$  exists if and only if  $\det(A) \neq 0$ 

$$\begin{pmatrix} a & b \\ c & d \end{pmatrix}^{-1} = \frac{1}{ad - bc} \begin{pmatrix} d & -b \\ -c & a \end{pmatrix}$$

Cramer's Rule (in whatever form you wish to remember it)

Linear independence:  $\alpha_1 \underline{x}_1 + \alpha_2 \underline{x}_2 + ... + \alpha_n \underline{x}_n = \mathbf{0}$  if and only if  $\alpha_i = 0$  for all i

Eigenvalues and eigenvectors: Av = rv and det(A - rI) = 0

Sum of eigenvalues of A = Trace of A

Product of eigenvalues of A = Determinant of A

Diagonal form  $D = P^{-1}AP$  exists if  $P^{-1}$  exists, ie if the eigenvalues of A are distinct.

The two key rules of vector spaces: if  $\underline{u}$  and  $\underline{v}$  lie in the space, then  $\underline{u} + \underline{v}$  and  $\underline{r}u$  must also lie in the space.

Fundamental Theorem of Linear Algebra Dim(Null(A)) = No. of columns in A - Rank(A)